

# On the Maz'ya inequalities: existence and multiplicity results for an elliptic problem involving cylindrical weights <sup>\*</sup>

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**Abstract.** In this paper we discuss existence and multiplicity of solutions to the following class of superlinear problems:

$$(1) \quad \begin{cases} -\operatorname{div}(|x|^a \nabla u) = |x|^{-b_a} u^{p-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ u > 0. \end{cases}$$

Here  $u = u(x, y) : \mathbb{R}^k \times \mathbb{R}^{N-k} \rightarrow \mathbb{R}$ ,  $1 \leq k < N$ ,  $b_a = N - p \frac{N-2+a}{2}$  and  $a > (2-N) \frac{k}{N}$ . The main tools are some Sobolev-type inequalities with cylindrical weights that were proved by Maz'ya in 1980.

We also get new existence results for the singular superlinear problem

$$(2) \quad \begin{cases} -\Delta v = \lambda |x|^{-2} v + |x|^{-b_0} v^{p-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ v > 0, \end{cases}$$

by compounding a simple functional change with our results for (1). Here  $\lambda \leq \left(\frac{k-2}{2}\right)^2$  and  $b_0 = N - p \frac{N-2}{2}$ . In particular, we give an alternative proof of a result by Tertikas and Tintarev [16] in case  $\lambda = \left(\frac{k-2}{2}\right)^2$ . For  $\lambda < \left(\frac{k-2}{2}\right)^2$  we prove some existence results of singular solutions  $v \in L^p(\mathbb{R}^N; |x|^{-b_0} d\xi)$ .

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## Introduction

Let  $k, N$  be positive integers with  $1 \leq k < N$ . We put  $\mathbb{R}^N = \mathbb{R}^k \times \mathbb{R}^{N-k}$ , and we denote points  $\xi$  in  $\mathbb{R}^N$  as pairs  $(x, y) \in \mathbb{R}^k \times \mathbb{R}^{N-k}$ . In this paper we study existence and multiplicity for problem

$$\begin{cases} -\operatorname{div}(|x|^\alpha \nabla u) = |x|^{-b_a} u^{p-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ u > 0, \end{cases} \quad (0.1)$$

where the exponent  $b_a$  is given by

$$b_a = b_a(p) := N - p \frac{N - 2 + a}{2}, \quad (0.2)$$

and the real parameters  $a, p$  satisfy

$$(2 - N) \frac{k}{N} < a \leq 2 - k, \quad \frac{2(N - k)}{N - 2 + a} < p \leq 2^*. \quad (0.3)$$

Here, as usual,  $2^* = +\infty$  if  $N = 2$ , and  $2^* = \frac{2N}{N-2}$  if  $N \geq 3$ .

If  $k = N$  problem (0.1) is related to the Caffarelli-Kohn-Nirenberg inequality [3]. There is a large number bibliographical references for (0.1) in this case: we quote for example [4], [6], [8], [17] and references there-in. Concerning the cylindrical case  $k < N$  we cite [1], [5], [11], [12], where  $2 \leq k < N$  and  $a = 0$  are assumed. In [16], Tertikas and Tintarev studied problem (0.1) for  $a = 2 - k$ ,  $N \geq 3$  and  $p = 2^*$ . In [15] some existence results of solutions  $u \in D_0^1(\mathbb{R}^N) \cap L^2(\mathbb{R}^N; |x|^{\alpha-2} d\xi)$  are given under the assumption  $a \neq 2 - k$ . Finally, the paper [10] is concerned with symmetric solutions.

Our interest in problem (0.1) is motivated by an inequality that is peculiar to the cylindrical case  $k < N$ , and that was proved by Maz'ya in [14] (see also [5] for the case  $k = 1$ ,

$N = 2$ ): if  $a, p, b_a \in \mathbb{R}$  satisfy

$$a > (2 - N) \frac{k}{N}, \quad \max \left\{ 2, \frac{2(N - k)}{N - 2 + a} \right\} < p \leq 2^*, \quad b_a = N - p \frac{N - 2 + a}{2}, \quad (0.4)$$

then there exists  $c_{a,p} > 0$  such that

$$c_{a,p} \left( \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi \right)^{2/p} \leq \int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi, \quad \forall u \in C_c^\infty(\mathbb{R}^N). \quad (0.5)$$

Thanks to inequality (0.5), we can define the Hilbert space  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$  by completing  $C_c^\infty(\mathbb{R}^N)$  with respect to the norm  $\|u\|^2 = \int_{\mathbb{R}^N} |x|^a |\nabla u|^2$ . Then, every minimizer for

$$S_{a,p}^D := \inf_{D_0^1(\mathbb{R}^N; |x|^a d\xi)} \frac{\int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi}{\left( \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi \right)^{2/p}} \quad (0.6)$$

is, up to a Lagrange multiplier, a solution to (0.1). In case  $a > 2 - k$ , the existence of solutions to (0.6) follows from Theorems B1 and B2 in [15]. In the present paper we focus our attention on the case  $a \leq 2 - k$ .

While studying (0.6) one has to take into account the action of the groups of dilations in  $\mathbb{R}^N$  and of translations in  $\mathbb{R}^{N-k}$ . Indeed, it is quite easy to exhibit non compact minimizing sequences. To overcome this difficulty we use a suitable Rellich type theorem and a rescaling argument. Our existence result is stated in Theorem 2.1. If  $N \geq 3$  and  $p = 2^*$ , the group of translations in the  $x$ -variable produces some extra lack of compactness phenomena. For this reason, to construct a compact minimizing sequence we need the additional assumption  $S_{a,2^*}^D < S$ , where  $S$  is the Sobolev constant. Some sufficient conditions for  $S_{a,2^*}^D < S$  can be found in Section 3.2. Our main existence result in the critical case is stated in Theorem 3.9.

In Section 3 we take  $a < 2 - k$  and we compare the solution  $u^D$  to the minimization problem (0.6) with the solution  $u^X \in D_0^1(\mathbb{R}^N; |x|^a d\xi) \cap L^2(\mathbb{R}^N; |x|^{\alpha-2} d\xi)$  to (0.1), whose existence was proved in [15]. Under suitable assumptions on the exponents  $a$  and  $p$ , we are able to prove that  $u^X$  do not solve (0.6). Following this idea we prove several multiplicity results for (0.1). This will be done in Section 3.1 for  $p < 2^*$  and in Section 3.2 in the limiting case  $N \geq 3, p = 2^*$ .

In the last Section we address our attention on the existence of classical solutions to

$$\begin{cases} -\Delta v = \lambda |x|^{-2} v + |x|^{-b_0} v^{p-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ v > 0, \end{cases} \quad (0.7)$$

where  $\lambda, p, b_0 \in \mathbb{R}$  satisfy

$$\lambda \leq \left( \frac{k-2}{2} \right)^2, \quad p \in (2, 2^*], \quad b_0 = N - p \frac{N-2}{2}.$$

First of all we use a functional change and Theorem 2.1 to prove the existence of a cylindrically symmetric solution for  $\lambda = \left(\frac{k-2}{2}\right)^2$  (see Theorem 4.1). Existence was already proved in [16] in case  $p = 2^*$ .

In Subsection 4.2 we state some existence results of singular solutions to (0.7) under the assumption  $\lambda < \left(\frac{k-2}{2}\right)^2$ . In this Introduction we just mention an unexpected consequence of our arguments in the limiting case  $p = 2^*$ . It is well known that problem

$$\begin{cases} -\Delta v = v^{2^*-1} & \text{in } \mathbb{R}^N \\ v > 0 \end{cases} \quad (0.8)$$

has a solution in  $D_0^1(\mathbb{R}^N)$  which is unique up to translations and up to changes of scale in  $\mathbb{R}^N$ . Moreover, its  $L^{2^*}$ -norm is  $S^{N/2}$ , where  $S$  is the Sobolev constant. In Corollary 4.4 we prove that, for  $N \geq 7$ , problem (0.8) has a smooth cylindrically symmetric solution  $v_\infty : (\mathbb{R}^3 \setminus \{0\}) \times \mathbb{R}^{N-3} \rightarrow \mathbb{R}$ , such that

$$\int_{\mathbb{R}^N} |\nabla v_\infty|^2 d\xi = +\infty, \quad \int_{\mathbb{R}^N} |v_\infty|^{2^*} d\xi < S^{N/2}.$$

**Notation** For any integer  $j \geq 1$ , we denote by  $B_R^j(z)$  the  $j$ -dimensional ball of radius  $R$  centered at  $z \in \mathbb{R}^j$ . We denote by  $\omega_j$  the surface measure of the unit sphere  $\mathbb{R}^j$ .

It will be often convenient to set

$$\mathbb{R}_0^N := (\mathbb{R}^k \setminus \{0\}) \times \mathbb{R}^{N-k}.$$

If  $p \in [1, +\infty)$ ,  $\alpha \in \mathbb{R}$ , and if  $\Omega$  is a domain in  $\mathbb{R}^N$ , then  $L^p(\Omega; |x|^\alpha d\xi)$  is the space of measurable maps  $u$  on  $\Omega$  with  $\int_\Omega |x|^\alpha |u|^p d\xi < +\infty$ . Therefore  $L^p(\Omega; |x|^0 d\xi) \equiv L^p(\Omega)$  is the standard Lebesgue space. The Hilbert space  $D_0^1(\Omega)$  is the closure of  $C_c^\infty(\Omega)$  with respect to the  $L^2$ -norm of  $\nabla u$ .

For  $N \geq 3$  the critical Sobolev exponent is  $2^* = \frac{2N}{N-2}$ . The Sobolev constant

$$S := \inf_{D_0^1(\mathbb{R}^N)} \frac{\int_{\mathbb{R}^N} |\nabla u|^2 d\xi}{\left(\int_{\mathbb{R}^N} |u|^{2^*} d\xi\right)^{2/2^*}},$$

is achieved by the map

$$v_T(x, y) := \left(1 + |x|^2 + |y|^2\right)^{-\frac{N-2}{2}}. \quad (0.9)$$

Accordingly with [12], a smooth map  $v$  on  $\mathbb{R}_0^N = (\mathbb{R}^k \setminus \{0\}) \times \mathbb{R}^{N-k}$  is said to be *cylindrically symmetric* if  $u(\cdot, y)$  is symmetric decreasing in  $\mathbb{R}^k$  for any choice of  $y \in \mathbb{R}^{N-k}$ , and if there exists  $y_0 \in \mathbb{R}^{N-k}$  such that  $u(x, \cdot)$  is symmetric decreasing about  $y_0 \in \mathbb{R}^{N-k}$ , for any choice of  $x \in \mathbb{R}^k \setminus \{0\}$ .

# 1 Preliminaries

One of the main features in problem (0.1) is its invariance with respect to transforms

$$u(x, y) \longrightarrow (T(\tau, \eta)u)(x, y) := \tau^{\frac{N-2+a}{2}} u(\tau x, \tau y + \eta), \quad (1.1)$$

where  $\tau \in (0, +\infty)$ ,  $\eta \in \mathbb{R}^{N-k}$ . In addition, it holds also that

$$\begin{aligned} \int_{\mathbb{R}^N} |x|^a |\nabla(T(\tau, \eta)u)|^2 d\xi &= \int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi, \\ \int_{\mathbb{R}^N} |x|^{-b_a} |T(\tau, \eta)u|^p d\xi &= \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi \end{aligned} \quad (1.2)$$

for any  $u \in C_c^\infty(\mathbb{R}^N)$ , whenever the weights  $|x|^a$  and  $|x|^{-b_a}$  are locally integrable on  $\mathbb{R}^N$ . Indeed, these invariances are responsible for the integral inequalities that are the starting point of the present paper and that were proved by Maz'ya [14] in 1980.

## 1.1 Maz'ya inequality. The space $D_0^1(\mathbb{R}^N; |x|^a d\xi)$

Assume that  $a, p, b_a$  in  $\mathbb{R}$  satisfy (0.4). Then the weights  $|x|^a$  and  $|x|^{-b}$  are locally integrable on  $\mathbb{R}^N$ . The *Maz'ya inequality* states that there exists  $c_{a,p} > 0$  such that

$$c_{a,p} \left( \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi \right)^{2/p} \leq \int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi, \quad \forall u \in C_c^\infty(\mathbb{R}^N). \quad (1.3)$$

Inequality (1.3) was proved by Maz'ya in [14], Section 2.1.6, Corollary 2, under the assumptions  $N \geq 3$  and  $p \leq 2^*$ . As observed in [5], Section 4, if  $N = 2$  and  $k = 1$ , then the same inequality holds true for any  $p \in (2, +\infty)$ .

Thanks to (1.3), for any  $a > (2 - N)\frac{k}{N}$  we can define the Hilbert space  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$  by completing  $C_c^\infty(\mathbb{R}^N)$  with respect to the scalar product

$$\langle u, v \rangle = \int_{\mathbb{R}^N} |x|^a \nabla u \cdot \nabla v d\xi.$$

Notice that for  $N \geq 3$ ,  $D_0^1(\mathbb{R}^N; |x|^0 d\xi) \equiv D_0^1(\mathbb{R}^N)$ . From (1.3) it follows that the infimum

$$S_{a,p}^D := \inf_{u \in D_0^1(\mathbb{R}^N; |x|^a d\xi)} \frac{\int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi}{\left( \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi \right)^{2/p}}$$

is positive, provided that  $a, p, b_a$  are as in (0.4). It is clear that if  $S_{a,p}^D$  is achieved by  $u \in D_0^1(\mathbb{R}^N; |x|^a d\xi)$  then  $u$  is a classical solution to (0.1), up to multiplicative constant. By standard elliptic regularity theory and by the maximum principle,  $u$  is smooth and positive on  $\{x \neq 0\}$ . In addition,  $u$  is a *weak solution* to (0.1) on  $\mathbb{R}^N$ , that is,

$$\int_{\mathbb{R}^N} |x|^a \nabla u \cdot \nabla \Phi d\xi = \int_{\mathbb{R}^N} |x|^{-b_a} u^{p-1} \Phi d\xi, \quad \forall \Phi \in C_c^\infty(\mathbb{R}^N), \quad (1.4)$$

and it is *entire*, namely,

$$\int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi = \int_{\mathbb{R}^N} |x|^{-b_a} u^p d\xi < +\infty .$$

The problem of the existence of minimizers for  $S_{a,p}^D$  will be discussed in Section 2.

## 1.2 Hardy-Sobolev-Maz'ya inequality. The space $X_0^1(\mathbb{R}^N; |x|^a d\xi)$

We first recall the *Hardy inequality* with cylindrical weights. It states that

$$\left( \frac{k-2+a}{2} \right)^2 \int_{\mathbb{R}^N} |x|^{a-2} |u|^2 d\xi \leq \int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi \quad (1.5)$$

for any  $u \in C_c^\infty(\mathbb{R}^N)$  if  $a > 2 - k$ , and for any  $u \in C_c^\infty(\mathbb{R}_0^N)$  if  $a \leq 2 - k$  (see for example [14], Section 2.1.6, or [7], Theorem 3.5). The constant

$$\lambda_1(a) := \left( \frac{k-2+a}{2} \right)^2 \quad (1.6)$$

is sharp, and it is not achieved. Notice that Hardy's inequality implies that  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$  is continuously embedded into  $L^2(\mathbb{R}^N; |x|^{a-2} d\xi)$ , provided that  $a > 2 - k$ .

The *Hardy-Sobolev-Maz'ya inequality* was proved in [14] (Section 2.1.6, Corollary 3) in case  $N \geq 3$ , and in Section 4 of [5] in case  $N = 2$ ,  $k = 1$ . It states that for any  $a \in \mathbb{R}$  and for every real exponent  $p \in (2, 2^*]$  there exists a constant  $c_{a,p} > 0$  such that

$$c_{a,p} \left( \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi \right)^{2/p} \leq \int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi - \lambda_1(a) \int_{\mathbb{R}^N} |x|^{a-2} |u|^2 d\xi \quad (1.7)$$

for any  $u \in C_c^\infty(\mathbb{R}^N)$  if  $a > 2 - k$ , and for any  $u \in C_c^\infty(\mathbb{R}_0^N)$  if  $a \leq 2 - k$ . We remark that (1.7) fails if  $k = N$ . We refer to [9] for a discussion on this subject.

Inequality (1.7) provides the starting point for applying variational methods to the singular problem

$$\begin{cases} -\operatorname{div}(|x|^a \nabla u) = \lambda |x|^{a-2} u + |x|^{-b_a} u^{p-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ u > 0, \end{cases} \quad (1.8)$$

where  $\lambda$  is a real parameter. For future convenience we recall here the approach used in [15] to study (1.8) in case  $\lambda < \lambda_1(a)$ . For any  $a \in \mathbb{R}$  define the Hilbert space

$$X_0^1(\mathbb{R}^N; |x|^a d\xi) := D_0^1(\mathbb{R}^N; |x|^a d\xi) \cap L^2(\mathbb{R}^N; |x|^{a-2} d\xi) .$$

Notice that  $X_0^1(\mathbb{R}^N; |x|^a d\xi) = D_0^1(\mathbb{R}^N; |x|^a d\xi)$  if  $a > 2 - k$ , by (1.5). It turns out that  $C_c^\infty((\mathbb{R}^k \setminus \{0\}) \times \mathbb{R}^{N-k})$  is dense in  $X_0^1(\mathbb{R}^N; |x|^a d\xi)$  ([15], Appendix B) and that (1.7) holds for any  $u \in X_0^1(\mathbb{R}^N; |x|^a d\xi)$ . The paper [15] deals with the existence of extremals for

$$\inf_{u \in X_0^1(\mathbb{R}^N; |x|^a d\xi)} \frac{\int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi - \lambda \int_{\mathbb{R}^N} |x|^{a-2} |u|^2 d\xi}{\left( \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi \right)^{2/p}}$$

under the assumption  $\lambda < \lambda_1(a)$ . In particular, for  $\lambda = 0$  and  $a \neq 2 - k$ , every solution  $u^X \in X_0^1(\mathbb{R}^N; |x|^a d\xi)$  to the minimization problem

$$S_{a,p}^X := \inf_{u \in X_0^1(\mathbb{R}^N; |x|^a d\xi)} \frac{\int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi}{\left( \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi \right)^{2/p}} \quad (1.9)$$

is, up to a Lagrange multiplier, an entire classical solution to (0.1). Notice also that  $u^X$  is a weak entire solution to (0.1) on  $(\mathbb{R}^k \setminus \{0\}) \times \mathbb{R}^{N-k}$ . If  $a \leq 2 - k$ , in general, one can not conclude that  $u^X$  is indeed a weak solution on the whole of  $\mathbb{R}^N$ . On the other hand, for  $a > 2 - k$  one can take advantage of the Hardy inequality (1.5) to show that  $S_{a,p}^D = S_{a,p}^X$ , and that  $u^X$  satisfies (1.4) (see [15], Theorem A.2).

Finally we notice that in general  $S_{a,p}^D \leq S_{a,p}^X$  for any  $a > (2 - N)\frac{k}{N}$ , since  $X_0^1(\mathbb{R}^N; |x|^a d\xi)$  is contained in  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$ . In Section 3 we illustrate some examples in which the strict inequality  $S_{a,p}^D < S_{a,p}^X$  holds true.

Concerning the existence of minimizers for  $S_{a,p}^X$  we can state the following result.

**Theorem 1.1** *Assume  $a \neq 2 - k$ , and let  $p > 2$ . The infimum  $S_{a,p}^X$  is achieved by a map  $u^X \in X_0^1(\mathbb{R}^N; |x|^a d\xi)$  provided that one of the following conditions holds:*

- a)  $N = 2$  or  $p \in (2, 2^*)$ ;
- b)  $N \geq 3$ ,  $p = 2^*$  and  $S_{a,2^*}^X < S$ .

Moreover, if  $k = 1$  then the support of  $u^X$  is a half-plane.

Theorem 1.1 is a direct consequence of Theorems B.1 and B.2 in [15] in case  $N \geq 3$ ; the same proof can be carried out in case  $N = 2$ ,  $k = 1$ .

We conclude this subsection with a few remarks on the infimum  $S_{a,p}^X$ . First we state a useful Lemma that was proved in [15], Appendix B.

**Lemma 1.2** *For any  $a \in \mathbb{R}$  the linear operator  $L_a(u) := |x|^{\frac{a}{2}} u$  is a bi-continuous isomorphism between  $X_0^1(\mathbb{R}^N; |x|^a d\xi)$  and  $X_0^1(\mathbb{R}^N; d\xi) = D_0^1(\mathbb{R}^N) \cap L^2(\mathbb{R}^N; |x|^{-2} d\xi)$ . Moreover,*

$$\int_{\mathbb{R}^N} |x|^a |\nabla u|^2 - \lambda_1(a) \int_{\mathbb{R}^N} |x|^{a-2} |u|^2 = \int_{\mathbb{R}^N} |\nabla(L_a u)|^2 - \lambda_1(0) \int_{\mathbb{R}^N} |x|^{-2} |L_a u|^2 \quad (1.10)$$

for any  $u \in X_0^1(\mathbb{R}^N; |x|^a d\xi)$ .

In the next lemma we point out some remarks on the behavior of the map  $a \rightarrow S_{a,p}^X$ .

**Lemma 1.3** *Assume  $2 < p < 2^*$ . Then the map  $a \rightarrow S_{a,p}^X$  is strictly increasing for  $a \geq 2 - k$ , and it is strictly decreasing for  $a \leq 2 - k$ .*

**Proof.** For  $a \in \mathbb{R}$  let  $\lambda_1(a)$  be as in (1.6). Set  $\bar{a} := 2(2-k) - a$  and notice that  $\lambda_1(a) = \lambda_1(\bar{a})$ . Then, by (1.10), it turns out that

$$\begin{aligned} S_{a,p}^X &= \inf_{v \in X_0^1(\mathbb{R}^N; d\xi)} \frac{\int_{\mathbb{R}^N} |\nabla v|^2 d\xi - (\lambda_1(0) - \lambda_1(a)) \int_{\mathbb{R}^N} |x|^{-2} v^2 d\xi}{\left( \int_{\mathbb{R}^N} |x|^{-b_a} |v|^p d\xi \right)^{2/p}} \\ &= \inf_{v \in X_0^1(\mathbb{R}^N; d\xi)} \frac{\int_{\mathbb{R}^N} |\nabla v|^2 d\xi - (\lambda_1(0) - \lambda_1(\bar{a})) \int_{\mathbb{R}^N} |x|^{-2} v^2 d\xi}{\left( \int_{\mathbb{R}^N} |x|^{-b_a} |v|^p d\xi \right)^{2/p}} = S_{\bar{a},p}^X. \end{aligned}$$

Thus  $S_{a,p}^X = S_{\bar{a},p}^X$ . The Lemma is readily proved, since the map  $a \rightarrow \lambda_1(a)$  is increasing for  $a \geq 2 - k$ , and since  $S_{a,p}^X$  is achieved for any  $a \neq 2 - k$ .  $\square$

The case  $N \geq 3$ ,  $p = 2^*$  is more difficult. We recall that  $S_{a,2^*}^X \leq S$  for any  $a \in \mathbb{R}$  (see [15], Theorem B.5), and that the map  $v_T$  defined in (0.9) achieves the best Sobolev constant  $S$  on  $D_0^1(\mathbb{R}^N)$ . Moreover  $v_T \in L^2(\mathbb{R}^N; |x|^{-2} d\xi)$ , that is,  $v_T \in X_0^1(\mathbb{R}^N; d\xi)$ , if and only if  $k \geq 3$ . In this case, a direct computation shows that the map

$$u_T(x, y) := |x|^{k-2} v_T(x, y)$$

belongs to  $X_0^1(\mathbb{R}^N; |x|^{2(2-k)} d\xi)$  and achieves  $S_{2(2-k),2^*}^X = S$ . On the contrary, if  $k = 1, 2$  then  $v_T \notin L^2(\mathbb{R}^N; |x|^{-2} d\xi)$ , and  $S_{0,2^*}^X = S_{2(2-k),2^*}^X = S$  are not achieved.

In the next Lemma we collect some remarks on the behavior of the map  $a \rightarrow S_{a,2^*}^X$ .

**Lemma 1.4** *Assume  $N \geq 3$  and let  $a \in \mathbb{R}$ . Then the map  $a \rightarrow S_{a,2^*}^X$  is increasing for  $a \geq 2 - k$ , and it is decreasing for  $a \leq 2 - k$ . Moreover:*

1.  $S_{a,2^*}^X \leq S$  for any  $a \in \mathbb{R}$ .
2.  $S_{a,2^*}^X = S$  and  $S_{a,2^*}^X$  is not achieved in the following cases:
  - $k = 1$  and  $N = 3$ , or  $k = 1$ ,  $N \geq 4$  and  $a \notin (0, 2)$ ;
  - $k = 2$
  - $k \geq 3$ ,  $a \notin [2(2 - k), 0]$ .
3.  $S_{a,2^*}^X$  is achieved in the following cases:
  - $k = 1$ ,  $N \geq 4$ ,  $a \in (0, 2)$ ,  $a \neq 1$ ;
  - $k \geq 3$ ,  $a \in [2(2 - k), 0]$ ,  $a \neq 2 - k$ .

**Proof.** The monotonicity properties of the map  $a \rightarrow S_{a,2^*}^X$  can be checked as in Lemma 1.3. For the proof of 1. we refer to [15], Theorem B.5. By contradiction, assume that  $k = 1$ ,  $N = 3$  and that  $S_{a,6}^X$  is achieved by a map  $u \in X_0^1(\mathbb{R}^3; |x|^a d\xi)$ , for some  $a \in \mathbb{R}$ . Then  $a \in (0, 2)$  by [15], Theorem B.5. Set  $v(x, y) = |x|^{a/2} u(x, y)$ . Then, by Proposition B.3 and



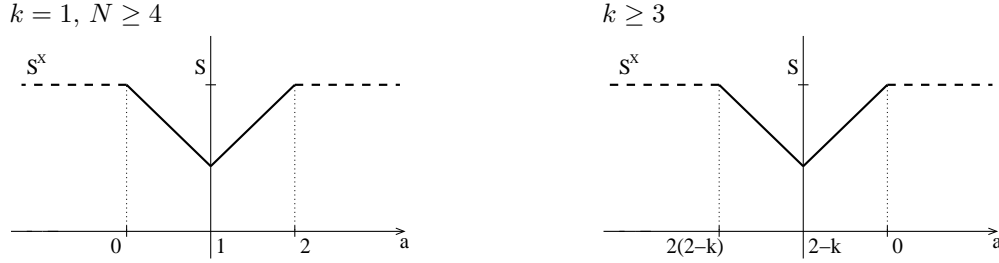
by Lemma 1.2 of [15], we can assume that the support of  $v$  is contained in the half space  $(0, +\infty) \times \mathbb{R}^2$ , and that  $v$  solves

$$\begin{cases} -\Delta v = \lambda|x|^{-2}v + v^5 & \text{in } (0, +\infty) \times \mathbb{R}^2 \\ v > 0 \\ v \in D_0^1((0, +\infty) \times \mathbb{R}^2), \end{cases}$$

where

$$\lambda = \frac{1}{4} - \left(\frac{a-1}{2}\right)^2, \quad 0 < \lambda < \frac{1}{4}.$$

This clearly contradicts the nonexistence result in [13], Section 6. The proofs of the remaining statements can be found in [15], Appendix B.  $\square$



**Fig.1** Graphics of  $a \rightarrow S_{a,2^*}^X$ . --- =  $S_{a,2^*}^X$  not achieved; — =  $S_{a,2^*}^X$  achieved.

### 1.3 The space $\hat{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k})$

For  $a = 0$  inequality (1.7) becomes

$$c_p \left( \int_{\mathbb{R}^N} |x|^{-b_0} |v|^p d\xi \right)^{2/p} \leq \int_{\mathbb{R}^N} [|\nabla v|^2 - \lambda_1(0)|x|^{-2}|v|^2] d\xi \quad (1.11)$$

for any  $v \in C_c^\infty(\mathbb{R}_0^N)$ , where, as before,  $\mathbb{R}_0^N = (\mathbb{R}^k \setminus \{0\}) \times \mathbb{R}^{N-k}$  and  $b_0 = N - p \frac{N-2}{2}$ .

Define as in [16] the Hilbert space  $\hat{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k})$  by completing  $C_c^\infty(\mathbb{R}_0^N)$  with respect to the scalar product

$$\langle u, v \rangle = \int_{\mathbb{R}^N} [\nabla u \cdot \nabla v - \lambda_1(0)|x|^{-2}uv] d\xi.$$

Notice that  $X_0^1(\mathbb{R}^N; d\xi) = D_0^1(\mathbb{R}^N) \cap L^2(\mathbb{R}^N; |x|^{-2}d\xi) \subset \hat{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k})$ . In particular,  $D_0^1(\mathbb{R}^N)$  is contained in  $\hat{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k})$  if and only if  $k \geq 2$ , and  $D_0^1(\mathbb{R}^N) = \hat{X}_0^1(\mathbb{R}^2 \times \mathbb{R}^{N-2})$  if  $k = 2$ . In Section 4.1 we will study the existence of extremals for the inequality (1.11). For future convenience we point out a Lemma.

**Lemma 1.5** *The linear operator  $L_{(k-2)}v := |x|^{\frac{k-2}{2}}v$  is a bi-continuous isomorphism between  $\hat{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k})$  and  $D_0^1(\mathbb{R}^N; |x|^{2-k}d\xi)$ . Moreover,*

$$\int_{\mathbb{R}^N} |x|^{2-k} |\nabla(L_{(k-2)}v)|^2 d\xi = \int_{\mathbb{R}^N} [|\nabla v|^2 - \lambda_1(0)|x|^{-2}|v|^2] d\xi \quad (1.12)$$

for any  $v \in \hat{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k})$ .

**Proof.** An application of the divergence theorem shows that (1.12) holds for any  $v \in C_c^\infty(\mathbb{R}_0^N)$ . We have to prove that  $C_c^\infty(\mathbb{R}_0^N)$  is dense in  $D_0^1(\mathbb{R}^N; |x|^{2-k}d\xi)$ . Fix any map  $v \in C_c^\infty(\mathbb{R}^N)$ . For  $\varepsilon > 0$  set

$$\varphi_\varepsilon(|x|) = \begin{cases} 0 & \text{if } |x| \leq \varepsilon^2 \\ \frac{\log|x|/\varepsilon^2}{|\log\varepsilon|} & \text{if } \varepsilon^2 < |x| < \varepsilon \\ 1 & \text{if } |x| \geq \varepsilon. \end{cases}$$

It is clear that  $\varphi_\varepsilon v \in D_0^1(\mathbb{R}^N; |x|^{2-k}d\xi)$  and that  $\nabla(v - \varphi_\varepsilon v) = (1 - \varphi_\varepsilon)\nabla v - v\nabla\varphi_\varepsilon \rightarrow 0$  a.e. on  $\mathbb{R}^N$  as  $\varepsilon \rightarrow 0$ . To prove that  $\varphi_\varepsilon v \rightarrow v$  in  $D_0^1(\mathbb{R}^N; |x|^{2-k}d\xi)$  it suffices to remark that

$$\int_{\mathbb{R}^N} |x|^{2-k} |v\nabla\varphi_\varepsilon|^2 d\xi \leq C_v \int_{\mathbb{R}^k} |x|^{2-k} |\varphi'_\varepsilon|^2 dx = O(|\log\varepsilon|^{-1}).$$

The conclusion follows via Lebesgue's theorem, since  $|(1 - \varphi_\varepsilon)\nabla v| \leq |\nabla v|$  on  $\mathbb{R}^N$ , and since  $|\nabla v| \in L^2(\mathbb{R}^N; |x|^{2-k}d\xi)$ .  $\square$

## 2 Existence results for (0.1)

The main result in this Section concerns the existence of extremal functions for the Maz'ya inequality.

**Theorem 2.1** *Assume that (0.3) is satisfied. Then  $S_{a,p}^D$  is achieved on  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$  by a weak entire solution  $u^D \in D_0^1(\mathbb{R}^N; |x|^a d\xi)$  to (0.1) provided that one of the following conditions are satisfied:*

- a)  $N = 2$  or  $p < 2^*$ ;
- b)  $N \geq 3$ ,  $p = 2^*$  and  $S_{a,2^*}^D < S$ .

**Remark 2.2** Assume in addition that  $k = 1$  and  $a = 0$ , hence  $p > 2(N-1)/(N-2)$ . Then the solution  $u^D$  in Theorem 2.1 is cylindrically symmetric by [10], Theorem 0.2. If  $k \geq 3$  and  $2(2-k) \leq a \leq 2-k$ , then  $u^D$  turns out to be radially symmetric in the  $x$ -variable, by Corollary 5.2 in [10].

**Remark 2.3** Assume  $N \geq 3$ ,  $p = 2^*$  and  $a \in ((2-N)k/N, 2-k]$ ,  $a \neq 0$ . If  $k = 1$  assume in addition that  $N \geq 4$  or  $a < 0$ . In Section 3.2 we will show that under these assumptions condition  $S_{a,2^*}^D < S$  is always satisfied. The case  $k = 1$ ,  $N = 3$  and  $a \in (0, 1]$  is still open.

The first step in the proof is a Rellich-type theorem.

**Lemma 2.4** *Assume  $\frac{2-N}{N}k < a \leq 2 - k$ , and let  $\Omega$  be a bounded domain. Then*

$$D_0^1(\mathbb{R}^N; |x|^a d\xi) \hookrightarrow L^2(\Omega, |x|^a d\xi)$$

with compact inclusion.

**Proof.** Fix a map  $u \in C_c^\infty(\mathbb{R}^N)$  and choose any exponent  $p > 2$ , satisfying also  $p \leq 2^*$  if  $N \geq 3$ . Let  $b_a = N - p\frac{N-2+a}{2}$  as in (0.2). Notice that

$$b_a + \frac{ap}{2} \geq 0 .$$

Thus, Hölder and Maz'ya inequalities give

$$\int_{\Omega} |x|^a |u|^2 d\xi \leq |\Omega|^{\frac{p}{p-2}} \left( \int_{\Omega} |x|^{\frac{ap}{2}} |u|^p d\xi \right)^{\frac{2}{p}} \leq c |\Omega|^{\frac{p}{p-2}} \int_{\mathbb{R}^N} |x|^a |\nabla u|^2 d\xi , \quad (2.1)$$

where  $|\Omega|$  is the Lebesgue measure of the domain  $\Omega$  and the constant  $c$  does not depend on  $u$ . This proves the continuity of the embedding. Now, let  $u_h$  be a sequence in  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$ , with  $u_h \rightarrow 0$  weakly in  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$ . For  $\varepsilon > 0$  small take a smooth function  $\varphi_\varepsilon \in C^\infty(\mathbb{R}^k)$  such that  $\varphi_\varepsilon(x) = 0$  if  $|x| \leq \varepsilon^2$ , and  $\varphi_\varepsilon(x) = 1$  if  $|x| \geq \varepsilon$ . Notice that for  $\varepsilon$  fixed it results that

$$\int_{\Omega} |x|^a |\varphi_\varepsilon u_h|^2 d\xi = o(1)$$

as  $h \rightarrow +\infty$  by the standard Rellich Theorem, since  $|x|$  is bounded away from 0 on the support of  $\varphi_\varepsilon$ . Set  $\Omega_\varepsilon := \{(x, y) \in \Omega \mid |x| < \varepsilon\}$ , and notice that

$$\begin{aligned} \int_{\Omega} |x|^a |u_h|^2 d\xi &= \int_{\Omega} |x|^a |\varphi_\varepsilon u_h + (1 - \varphi_\varepsilon) u_h|^2 d\xi \\ &\leq 2 \int_{\Omega} |x|^a |\varphi_\varepsilon u_h|^2 d\xi + 2 \int_{\Omega_\varepsilon} |x|^a |1 - \varphi_\varepsilon|^2 |u_h|^2 d\xi \\ &\leq o(1) + c \int_{\Omega_\varepsilon} |x|^a |u_h|^2 d\xi . \end{aligned}$$

Next, fix  $p > 2$  as before, and argue as for (2.1) to get

$$\int_{\Omega} |x|^a |u_h|^2 d\xi \leq o(1) + c |\Omega_\varepsilon|^{\frac{p}{p-2}} \int_{\mathbb{R}^N} |x|^a |\nabla u_h|^2 d\xi .$$

Notice that the sequence  $u_h$  is bounded in  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$  and that  $|\Omega_\varepsilon| \rightarrow 0$  as  $\varepsilon \rightarrow 0$ . Therefore, passing to the limit first as  $h$  go to 0, and then as  $\varepsilon \rightarrow 0$ , we get that

$$\int_{\Omega} |x|^a |u_h|^2 d\xi \rightarrow 0,$$

that proves the compactness of the embedding. □

The next Lemma will allow us to use suitable test functions.

**Lemma 2.5** *If  $\Psi \in C_c^\infty(\mathbb{R}^N)$  then  $\Psi u \in D_0^1(\mathbb{R}^N; |x|^a d\xi)$  for any  $u \in D_0^1(\mathbb{R}^N; |x|^a d\xi)$ .*

**Proof.** We can approximate any fixed  $u \in D_0^1(\mathbb{R}^N; |x|^a d\xi)$  with a sequence  $u_h \in C_c^\infty(\mathbb{R}^N)$ . Using Lemma 2.4 it is easy to prove that  $\Psi u_h \rightarrow \Psi u$  in  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$ , hence  $\Psi u \in D_0^1(\mathbb{R}^N; |x|^a d\xi)$ .  $\square$

The main step in the proof of Theorem 2.1 is the following Lemma. It is based on a rescaling argument that is quite close to that used in [15].

**Lemma 2.6** *Let  $u_h$  be a bounded sequence in  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$ , and let  $f_h \rightarrow 0$  be a sequence in the dual of  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$ . Assume that for  $a, p, b_a$  as in (0.3), (0.2) it holds that*

$$-\operatorname{div}(|x|^a \nabla u_h) = |x|^{-b_a} |u_h|^{p-2} u_h + f_h .$$

*Then either (up to a subsequence)  $u_h \rightarrow 0$  strongly in  $L^p(\mathbb{R}^N; |x|^{-b_a} d\xi)$ , or there exist sequences  $(t_h)_h \subset (0, +\infty)$  and  $(\eta_h)_h \subset \mathbb{R}^{N-k}$ , such that*

$$\lim_{h \rightarrow +\infty} \int_K |x|^{-b_a} |\tilde{u}_h|^p d\xi > 0 ,$$

where  $\tilde{u}_h(x, y) = t_h^{\frac{N-2+a}{2}} u_h(t_h x, t_h y + \eta_h)$  and

$$K = \{(x, y) \in \mathbb{R}^k \times \mathbb{R}^{N-k} \mid \frac{1}{2} < |x| < 1, |y| < 1\} .$$

**Proof.** We can assume that there exists  $u \in D_0^1(\mathbb{R}^N; |x|^a d\xi)$  such that  $u_h \rightarrow u$  weakly in  $D_0^1(\mathbb{R}^N; |x|^a d\xi)$  and in  $L^p(\mathbb{R}^N; |x|^{-b_a} d\xi)$ . Notice that  $u$  solves (0.1). If  $u \neq 0$  then we are done, since by elliptic regularity theory and by the standard maximum principle  $u$  can not vanish on  $K$ . Therefore, we only have to investigate the case  $u = 0$ ,  $\lim_{h \rightarrow +\infty} \int_{\mathbb{R}^N} |x|^{-b_a} |u_h|^p d\xi > 0$ . We argue as follows. Firstly we fix some  $\varepsilon_0 > 0$  in such a way that

$$\varepsilon_0^{\frac{p}{p-2}} < \lim_{h \rightarrow +\infty} \int_{\mathbb{R}^N} |x|^{-b_a} |u_h|^p d\xi, \quad 2\varepsilon_0 < S_{a,p}^D .$$

Using in a standard way the concentration function

$$Q_h(t) := \sup_{\eta \in \mathbb{R}^{N-k}} \int_{B_t^k(0) \times B_t^{N-k}(\eta)} |x|^{-b_a} |u_h|^p d\xi ,$$

it is possible to select sequences  $t_h > 0$  and  $\eta_h \in \mathbb{R}^{N-k}$  such that, for a subsequence, the rescaled sequence

$$\tilde{u}_h(x, y) := t_h^{\frac{N-2+a}{2}} u_h(t_h x, t_h y + \eta_h)$$

is bounded in  $D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$  (with the same  $D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$  and  $L^p(\mathbb{R}^N; |x|^{-b_a} d\xi)$ -norms as  $u_h$ ), and satisfies

$$\int_{B_1^k(0) \times B_1^{N-k}(y)} |x|^{-b_a} |\tilde{u}_h|^p d\xi \leq (2\varepsilon_0)^{\frac{p}{p-2}} \quad \forall y \in \mathbb{R}^{N-k}, \quad (2.2)$$

$$\int_{B_1^k(0) \times B_1^{N-k}(0)} |x|^{-b_a} |\tilde{u}_h|^p d\xi \geq (\varepsilon_0)^{\frac{p}{p-2}} > 0, \quad (2.3)$$

$$-\operatorname{div}(|x|^\alpha \nabla \tilde{u}_h) = |x|^{-b_a} |\tilde{u}_h|^{p-2} \tilde{u}_h + \tilde{f}_h, \quad (2.4)$$

with  $\tilde{f}_h \rightarrow 0$  in the dual of  $D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$ . As before, if (up to a subsequence) it happens that  $\tilde{u}_h \rightarrow \tilde{u} \neq 0$  then we are done. If  $\tilde{u}_h \rightarrow 0$ , we choose a finite number of points  $y_1, \dots, y_s \in \mathbb{R}^{N-k}$  in such a way that

$$\overline{B_1^{N-k}(0)} \subset \bigcup_{j=1}^s B_{1/2}^{N-k}(y_j). \quad (2.5)$$

Let  $\psi_1, \dots, \psi_s$  be cut-off functions, such that  $\psi_j = \psi_j(y) \in C_c^\infty(B_1^{N-k}(y_j))$ ,  $\psi_j \equiv 1$  on  $B_{1/2}^{N-k}(y_j)$ ,  $0 \leq \psi_j \leq 1$ . Also, fix a map  $\varphi = \varphi(x) \in C_c^\infty(B_1^k(0))$  s.t.  $0 \leq \varphi \leq 1$  and  $\varphi \equiv 1$  on  $B_{1/2}^k(0)$ . Thanks to Lemma 2.5 we can use  $\varphi^2 \psi_j^2 \tilde{u}_h$  as test function in (2.4) to find

$$\int_{\mathbb{R}^N} |x|^\alpha \nabla \tilde{u}_h \cdot \nabla (\varphi^2 \psi_j^2 \tilde{u}_h) d\xi = \int_{\mathbb{R}^N} |x|^{-b_a} |\tilde{u}_h|^{p-2} |\varphi \psi_j \tilde{u}_h|^2 d\xi + o(1).$$

Notice that

$$\begin{aligned} \int_{\mathbb{R}^N} |x|^\alpha \nabla \tilde{u}_h \cdot \nabla (\varphi^2 \psi_j^2 \tilde{u}_h) d\xi &= \int_{\mathbb{R}^N} |x|^\alpha |\nabla (\varphi \psi_j \tilde{u}_h)|^2 d\xi \\ &\quad - \int_{\mathbb{R}^N} |x|^\alpha |\tilde{u}_h|^2 (|\psi_j \nabla_x \varphi|^2 + |\varphi \nabla_y \psi_j|^2) d\xi \\ &= \int_{\mathbb{R}^N} |x|^\alpha |\nabla (\varphi \psi_j \tilde{u}_h)|^2 d\xi + o(1) \end{aligned}$$

by Lemma 2.4. Then, we use Hölder inequality, (2.2), and the definition of  $S_{a,p}^D$  to infer that

$$S_{a,p}^D \left( \int_{\mathbb{R}^N} |x|^{-b_a} |\varphi \psi_j \tilde{u}_h|^p d\xi \right)^{\frac{2}{p}} \leq 2\varepsilon_0 \left( \int_{\mathbb{R}^N} |x|^{-b_a} |\varphi \psi_j \tilde{u}_h|^p d\xi \right)^{\frac{2}{p}} + o(1).$$

Since  $2\varepsilon_0 < S_{a,p}^D$  this implies that  $\int_{\mathbb{R}^N} |x|^{-b_a} |\varphi \psi_j \tilde{u}_h|^p d\xi = o(1)$ , and therefore, by (2.5),

$$\int_{B_{1/2}^k(0) \times B_1^{N-k}(0)} |x|^{-b_a} |\tilde{u}_h|^p d\xi \leq \sum_{j=1}^s \int_{B_{1/2}^k(0) \times B_{1/2}^{N-k}(y_j)} |x|^{-b_a} |\tilde{u}_h|^p d\xi = o(1).$$

Finally, from (2.3) we get

$$0 < \varepsilon_0^{\frac{p}{p-2}} < \int_{B_1^k(0) \times B_1^{N-k}(0)} |x|^{-b_a} |\tilde{u}_h|^p d\xi = \int_K |x|^{-b_a} |\tilde{u}_h|^p d\xi + o(1).$$

Lemma 2.6 is completely proved.  $\square$

**Proof of Theorem 2.1.** We notice that entire solutions to equation (0.1) can be found as critical points of the  $C^1$  functional  $E : D_0^1(\mathbb{R}^N; |x|^\alpha d\xi) \rightarrow \mathbb{R}$  given by

$$E(u) = \frac{1}{2} \int_{\mathbb{R}^N} |x|^\alpha |\nabla u|^2 d\xi - \frac{1}{p} \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi .$$

Using standard arguments one can prove the following statements:

*i)* the functional  $E$  has a mountain pass geometry, with mountain pass level

$$c = \frac{p-2}{2p} (S_{a,p}^D)^{\frac{p}{p-2}} > 0 ;$$

*ii)* every Palais-Smale sequence for  $E$  is bounded in  $D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$  ;

*iii)* if  $u_h$  is a Palais-Smale sequence for  $E$  with  $E(u_h) \rightarrow c$  and  $u_h \rightarrow u \neq 0$  weakly in  $D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$ , then  $u$  is a critical point of  $E$  with  $E(u) = c$ , it achieves  $S_{a,p}^D$ , it is a ground state solution to (0.1) and it does not change sign.

Let  $u_h$  be a Palais Smale sequence at the mountain pass level  $c = \frac{p-2}{2p} (S_{a,p}^D)^{\frac{p}{p-2}}$ . We can assume that  $u_h \rightarrow u$  weakly in  $D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$  for some  $u \in D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$ . Notice that  $u_h$  can not converge strongly to 0, since  $c > 0$ . Thus, by Lemma 2.6 we can assume that

$$\lim_{h \rightarrow +\infty} \int_K |x|^{-b_a} |u_h|^p d\xi > 0$$

up to a change of coordinates, where  $K = \{(x, y) \in \mathbb{R}^k \times \mathbb{R}^{N-k} \mid \frac{1}{2} < |x| < 1, |y| < 1\}$ . If  $p < 2^*$ , we can use Rellich Theorem to get

$$\int_K |x|^{-b_a} |u|^p d\xi = \lim_{h \rightarrow +\infty} \int_K |x|^{-b_a} |u_h|^p d\xi > 0 .$$

This proves that  $u \neq 0$  and concludes the proof of *a)* in Theorem 2.1.

Now we assume  $N \geq 3$ ,  $p = 2^*$  and  $S_{a,2^*}^D < S$ . We claim that also in this case  $u \neq 0$ . By contradiction, assume that  $u_h \rightarrow 0$  weakly in  $D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$ . Choose smooth maps  $\varphi \in C_c^\infty(\mathbb{R}^k)$  and  $\psi \in C_c^\infty(\mathbb{R}^{N-k})$  in such a way that  $\varphi(x) = 0$  for  $|x| \leq \frac{1}{4}$ ,  $\varphi(x) = 1$  for  $\frac{1}{2} \leq |x| \leq 1$ ,  $\psi(y) = 1$  for  $|y| \leq 1$ . Notice that  $\varphi\psi \equiv 1$  on the rectangle  $K$ . Then compute  $E'(u_h) \cdot (\varphi^2 \psi^2 u_h) = o(1)$  and argue as in the proof of Lemma 2.6 to get

$$\int_{\mathbb{R}^N} |x|^\alpha |\nabla(\varphi\psi u_h)|^2 d\xi \leq S_{a,2^*}^D \left( \int_{\mathbb{R}^N} |x|^{\frac{N\alpha}{N-2}} |\varphi\psi u_h|^{2^*} d\xi \right)^{\frac{2}{2^*}} + o(1) . \quad (2.6)$$

Since  $\varphi \equiv 0$  in a neighborhood of the singular set  $\{x = 0\}$ , via direct computation based on the divergence Theorem, one can prove that

$$\int |x|^\alpha |\nabla(\varphi\psi u_h)|^2 = \int |\nabla(|x|^{\frac{\alpha}{2}} \varphi\psi u_h)|^2 - (\lambda_1(0) - \lambda_1(a)) \int |x|^{a-2} |\varphi\psi u_h|^2,$$

where  $\lambda_1(0), \lambda_1(a)$  are defined in (1.6). Thus,

$$\int |x|^\alpha |\nabla(\varphi\psi u_h)|^2 = \int |\nabla(|x|^{\frac{\alpha}{2}} \varphi\psi u_h)|^2 + o(1) \geq S \left( \int_{\mathbb{R}^N} |x|^{\frac{N\alpha}{N-2}} |\varphi\psi u_h|^{2^*} d\xi \right)^{\frac{2}{2^*}} + o(1)$$

by Rellich Theorem and Sobolev inequality. Therefore, from (2.6) we finally get

$$S \left( \int_{\mathbb{R}^N} |x|^{\frac{N\alpha}{N-2}} |\varphi\psi u_h|^{2^*} d\xi \right)^{\frac{2}{2^*}} \leq S_{a,2^*}^D \left( \int_{\mathbb{R}^N} |x|^{\frac{N\alpha}{N-2}} |\varphi\psi u_h|^{2^*} d\xi \right)^{\frac{2}{2^*}} + o(1),$$

that implies

$$\int_K |x|^{\frac{N\alpha}{N-2}} |u_h|^{2^*} d\xi \leq \int_{\mathbb{R}^N} |x|^{\frac{N\alpha}{N-2}} |\varphi(x)\psi(y)u_h|^{2^*} d\xi = o(1),$$

since  $S_{a,2^*}^D < S$  by assumption. This is a contradiction that concludes the proof of b).  $\square$

### 3 Multiplicity for (0.1)

In this Section we deal with entire classical solutions to (0.1). More precisely, we look for multiple smooth maps  $u$  on  $(\mathbb{R}^k \setminus \{0\}) \times \mathbb{R}^{N-k}$ , that satisfy (0.1) pointwise, and such that

$$\int_{\mathbb{R}^N} |x|^\alpha |\nabla u|^2 d\xi = \int_{\mathbb{R}^N} |x|^{-b\alpha} |u|^p d\xi < +\infty. \quad (3.1)$$

We recall that problem (0.1) as well as the integrals in (3.1) are invariant with respect to the  $(N-k+1)$ -dimensional group  $G_k = \{T(\tau, \eta) \mid \tau > 0, \eta \in \mathbb{R}^{N-k}\}$  of transforms given by (1.1) (see however the remarks below for the case  $k=1$ ). We shall always identify solutions  $u$  which belong to the orbit of the same transform  $T$  in  $G_k$ .

Our strategy to prove multiplicity results for (0.1) is to compare the solution  $u^D \in D_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$  of Theorem 2.1 with the solution  $u^X \in X_0^1(\mathbb{R}^N; |x|^\alpha d\xi)$  of [15]. More precisely, we look for conditions on  $a, p$  that guarantee that

$$S_{a,p}^D < S_{a,p}^X.$$

We start with a simple remark.

**Lemma 3.1** *1. Let  $p \in (2, 2^*]$  with  $p < +\infty$  if  $N=2$ . Then there exists  $\varepsilon > 0$  such that*

$$S_{a,p}^D < S_{a,p}^X \text{ if}$$

$$0 < a - 2 + N - \frac{2(N-k)}{p} < \varepsilon.$$

*2. Let  $a \in ((2-N)\frac{k}{N}, 2-k)$ . Then exists  $\varepsilon > 0$  such that  $S_{a,p}^D < S_{a,p}^X$  if*

$$0 < p - \frac{2(N-k)}{N-2+a} < \varepsilon.$$

**Proof.** Fix any map  $w \in C_c^\infty(\mathbb{R}^N)$  such that  $w \equiv 1$  on  $\{(x, y) \mid |x| \leq 1, |y| \leq 1\}$ . Then compute

$$S_{a,p}^D \leq \frac{\int_{\mathbb{R}^N} |x|^a |\nabla w|^2 d\xi}{\left(\int_{\mathbb{R}^N} |x|^{-b_a} |w|^p d\xi\right)^{2/p}} \leq \frac{C}{\left(\int_{\{|x|<1\}} |x|^{-b_a} dx\right)^{2/p}},$$

and notice that the weight  $|x|^{-b_a}$  loses its summability at the origin as  $b_a \rightarrow k$ . Therefore  $S_{a,p}^D \rightarrow 0$  as  $(N-2+a)p \rightarrow 2(N-k)$ . The conclusion readily follows from Lemma 1.3.  $\square$

The uniqueness result in the recent paper [12] by Mancini and Sandeep allows us to compute exactly the value of the infimum  $S_{2-k,p_k}^D$ , where

$$p_k = \frac{2(N-k+1)}{N-k} \quad (3.2)$$

(compare with (3.8) below). In the next Lemma we use this information to estimate  $S_{a,p_k}^D$  from above when  $a < 2-k$ .

**Lemma 3.2** *Assume  $2 \leq k < N$ ,  $N > 2(k-1)$  and  $1-k + \frac{1}{N-k+1} < a < 2-k$ . Then*

$$S_{a,p_k}^D < S_{a,p_k}^X.$$

**Proof.** Notice that  $p_k < 2^*$ . Thus, by Theorem 2.1, the infimum  $S_{2-k,p_k}^D$  is achieved by a map  $u$  that solves, up to a Lagrange multiplier, the degenerate problem

$$\begin{cases} -\operatorname{div}(|x|^{2-k} \nabla u) = |x|^{1-k} u^{p_k-1} & \text{in } \mathbb{R}^N, \quad x \neq 0 \\ u > 0 \\ u \in D_0^1(\mathbb{R}^N; |x|^{2-k} d\xi). \end{cases}$$

Set  $v(x, y) := |x|^{\frac{2-k}{2}} u(x, y)$ . Then by direct computation and by Lemma 1.2 it turns out that  $v$  solves the elliptic singular problem

$$\begin{cases} -\Delta v = \left(\frac{k-2}{2}\right)^2 |x|^{-2} + |x|^{-b_0} v^{p_k-1} & \text{in } \mathbb{R}^N \\ v > 0 \\ v \in \dot{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k}), \end{cases} \quad (3.3)$$

where  $b_0 = \frac{N-2k-2}{N-k}$ . By Theorem 0.3 in [10],  $v$  is cylindrically symmetric and therefore, by the uniqueness result in [13], Section 6, it turns out that

$$v(x, y) = c(\lambda, N, k) |x|^{\frac{2-k}{2}} \left((1+|x|)^2 + |y|^2\right)^{-\frac{N-k}{2}},$$

for some constant  $c(\lambda, N, k)$  that can be computed explicitly. As a consequence, we have that the map

$$u_M(x, y) := \left((1+|x|)^2 + |y|^2\right)^{-\frac{N-k}{2}}$$



achieves the best constant  $S_{2-k, p_k}^D$ . Now we set, for  $a \leq 2 - k$ ,

$$R_a := \frac{\int_{\mathbb{R}^N} |x|^a |\nabla u_M|^2 d\xi}{\left(\int_{\mathbb{R}^N} |x|^{-b_a} |u_M|^{p_k} d\xi\right)^{\frac{2}{p_k}}}. \quad (3.4)$$

We are going to prove by direct computation that  $R_a < R_{2-k}$  for  $a < 2 - k$ , hence

$$S_{a, p_k}^D \leq R_a < R_{2-k} = S_{2-k, p_k}^D.$$

Since  $S_{2-k, p_k}^D \leq S_{2-k, p_k}^X$ , and since the map  $a \rightarrow S_{2-k, p_k}^X$  decreases for  $a \leq 2 - k$ , this will lead to conclude the proof of the Lemma.

To compute  $R_a$  we set  $r = |x|$  and  $s = |y|$  and we notice that

$$\begin{aligned} \int_{\mathbb{R}^N} |x|^a |\nabla u_M|^2 d\xi &= c_{N, k} (N - k)^2 \int_0^{+\infty} r^{a+k-1} dr \int_0^{+\infty} \frac{s^{N-k-1}}{((1+r)^2 + s^2)^{N-k+1}} ds \\ &= c_{N, k} (N - k)^2 \Gamma \int_0^{+\infty} \frac{r^{a+k-1} dr}{(1+r)^{N-k+2}}, \end{aligned}$$

where  $c_{N, k} = \omega_k \omega_{N-k}$  and

$$\Gamma := \int_0^{+\infty} \frac{t^{N-k-1} dt}{(1+t^2)^{N-k+1}}.$$

Therefore one gets, via integration by parts,

$$\int_{\mathbb{R}^N} |x|^a |\nabla u_M|^2 d\xi = c_{N, k} \Gamma (N - k)^2 \frac{a + k - 1}{N - 2k + 2 - a} \int_0^{+\infty} \frac{r^{a+k-2} dr}{(1+r)^{N-k+2}}. \quad (3.5)$$

Notice that for  $p = p_k$  it turns out that  $b_a = b_a(p_k) = N - p_k \frac{N-2+a}{2} = -\frac{ap_k}{2} + \frac{N-2k+2}{N-k}$ . Therefore we are lead to compute

$$\begin{aligned} \int_{\mathbb{R}^N} |x|^{-b_a(p_k)} |u_M|^{p_k} d\xi &= c_{N, k} \int_0^{+\infty} r^{\frac{ap_k}{2} + (k-2)\frac{N-k+1}{N-k}} dr \int_0^{+\infty} \frac{s^{N-k-1}}{((1+r)^2 + s^2)^{N-k+1}} ds \\ &= c_{N, k} \Gamma \Phi_a, \end{aligned} \quad (3.6)$$

where

$$\Phi_a := \int_0^{+\infty} \frac{r^{\frac{a+k-2}{2} p_k} dr}{(1+r)^{N-k+2}}.$$

Now we use Hölder inequality (with conjugate exponents  $p_k/2$  and  $N - k + 1$ ) to estimate

$$\Phi_a \leq \left( \int_0^{+\infty} \frac{dr}{(1+r)^{N-k+2}} \right)^{\frac{1}{N-k+1}} \left( \int_0^{+\infty} \frac{r^{\frac{a+k-2}{2} p_k} dr}{(1+r)^{N-k+2}} \right)^{\frac{2}{p_k}}.$$

Therefore

$$\int_{\mathbb{R}^N} |x|^a |\nabla u_M|^2 d\xi \leq c_{N, k} \Gamma (N - k)^2 \frac{a + k - 1}{N - 2k + 2 - a} \left( \frac{1}{N - k + 1} \right)^{\frac{1}{N-k+1}} (\Phi_a)^{\frac{2}{p_k}}. \quad (3.7)$$

From (3.5) and (3.6) we infer that

$$S_{2-k, p_k}^D = R_{2-k} = (N-k) \left[ \frac{c_{N,k} \Gamma}{N-k+1} \right]^{\frac{1}{N-k+1}}. \quad (3.8)$$

On the other hand, from (3.7) we get also

$$S_{a, p_k}^D \leq R_a \leq \left[ \frac{c_{N,k} \Gamma}{N-k+1} \right]^{\frac{1}{N-k+1}} \frac{(N-k)^2(a+k-1)}{N-2k+2-a} = S_{2-k, p_k}^D \frac{(N-k)(a+k-1)}{N-2k+2-a}.$$

The conclusion follows from Lemma 1.3, by noticing that the map  $a \rightarrow \frac{a+k-1}{N-2k+2-a}$  is strictly increasing.  $\square$

It is now convenient to distinguish the case  $p < 2^*$  from the limiting case  $p = 2^*$ .

### 3.1 Multiplicity for $p < 2^*$

The next Corollary is an immediate consequence of Lemma 3.1 and of Theorem 2.1.

**Corollary 3.3** *Assume  $1 \leq k < N$  and  $p \in (2, 2^*)$ . Then there exists  $\varepsilon > 0$  such that if*

$$(N-k)\frac{2}{p} - (N-2) < a < (N-k)\frac{2}{p} - (N-2) + \varepsilon,$$

*then problem (0.1) has at least two distinct (modulo  $G_k$ ) entire classical solutions.*

Next we point out an immediate Corollary to Lemma 3.2 when  $p = p_k$  is given by (3.2).

**Corollary 3.4** *Let  $2 \leq k < N$ ,  $N > 2(k-1)$ ,  $1-k + \frac{1}{N-k+1} < a < 2-k$ , and let  $p_k$  be as in (3.2). Then problem (0.1) has at least two distinct (modulo  $G_2$ ) entire solutions*

$$u^X \in X_0^1(\mathbb{R}^N; |x|^a d\xi), \quad u^D \in D_0^1(\mathbb{R}^N; |x|^a d\xi) \setminus X_0^1(\mathbb{R}^N; |x|^a d\xi).$$

Finally, we focus our attention on the case  $k = 1$ , when the singular set  $\{x = 0\}$  is an hyperplane that disconnects the domain. Notice that indeed a larger noncompact group  $G_1$  of invariances acts on problem (0.1). More precisely, transformations in  $G_1$  depend on  $2N$  parameters, and are of the form

$$u(x, y) \longrightarrow (T(\tau_-, \tau_+, \eta_-, \eta_+)u)(x, y) := \begin{cases} \tau_-^{\frac{N-2+a}{2}} u(\tau_-x, \tau_-y + \eta_-) & \text{if } x < 0, \\ \tau_+^{\frac{N+2+a}{2}} u(\tau_+x, \tau_+y + \eta_+) & \text{if } x > 0, \end{cases}$$

for  $\tau_-, \tau_+ \in (0, +\infty)$ , and for  $\eta_-, \eta_+ \in \mathbb{R}^{N-k}$ . In other words, dilations in  $\xi$  and translations in  $y$  can be made independently for  $x < 0$  and  $x > 0$ , so that the equation in (0.1) is still invariant. Essentially the same remark has been made by Catrina and Wang in [6] for an O.D.E. involving spherically symmetric weights.

By Remark 2.2 we get that  $u^D \in D_0^1(\mathbb{R}^N)$  is cylindrically symmetric whenever  $u^D$  achieves the best constant  $S_{0,p}^D$ . On the other hand, by Lemma 1.2 in [15], if  $u^X \in X_0^1(\mathbb{R}^N; |x|^0 d\xi)$  achieves  $S_{0,p}^X$ , then the support of  $u^X$  is contained in a half-space, and hence it cannot achieve  $S_{0,p}^D$ . This proved the next result.

**Theorem 3.5** *Assume  $k = 1$ ,  $N \geq 3$ , and  $2_* < p < 2^*$ . Then problem*

$$\begin{cases} -\Delta u = |x|^{-b_0} u^{p-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ u > 0, \end{cases}$$

with  $b_0 = N - p\frac{N-2}{2}$ , has at least two distinct (modulo  $G_1$ ) entire classical solutions:

$$\begin{aligned} u^X &\in D_0^1((0, +\infty) \times \mathbb{R}^{N-1}), \text{ with } u^X(x, y) \equiv 0 \text{ for } x < 0, \\ u^D &\in D_0^1(\mathbb{R}^N), \text{ with } u^D(x, y) = u^D(-x, y). \end{aligned}$$

### 3.2 Existence and multiplicity for $p = 2^*$

In this Section we deal with the limiting case  $p = 2^*$ , that is, we study problem

$$\begin{cases} -\operatorname{div}(|x|^a \nabla u) = |x|^{\frac{Na}{N-2}} u^{2^*-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ u > 0. \end{cases} \quad (3.9)$$

Theorem 2.1 provides the existence of a solution to (3.9) whenever

$$S_{a,2^*}^D < S. \quad (3.10)$$

Notice that a first set of sufficient conditions for (3.10) can be easily obtained from Lemma 1.4. By this argument and by the symmetry result in [10] one can prove the following result (see also [16] for existence).

**Theorem 3.6** *Assume  $N \geq 4$  and  $k \neq 2$ . Then the infimum  $S_{2-k,2^*}^D$  is achieved by an entire solution  $u$  to*

$$\begin{cases} -\operatorname{div}(|x|^{2-k} \nabla u) = |x|^{-N\frac{k-2}{N-2}} u^{2^*-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ u > 0. \end{cases}$$

Moreover  $u$  is symmetric:  $u(x, y) = u(|x|, |y|)$ , and decreasing in the  $|y|$ -variable.

From now on we take  $a < 2 - k$ . Recall that  $S_{a,2^*}^X$  is achieved by Theorem 1.1 if  $S_{a,2^*}^X < S$ . Thus, besides (3.10), that gives existence, we are lead to investigate if it may happen that

$$S_{a,2^*}^D < S_{a,2^*}^X < S. \quad (3.11)$$

Indeed, (3.11) would give multiplicity for (3.9). The aim of this Section is to estimate from above  $S_{a,2^*}^D$  in order to find sufficient conditions for (3.10) or for (3.11). This will be done through two Lemmata.

**Lemma 3.7** *Inequality (3.10) holds true if*

$$(2 - N) \frac{k}{N} < a \leq 2 - k \quad \text{and} \quad a < 0 .$$

**Proof.** We are going to estimate the infimum  $S_{a,p}^D$  by using the map

$$v_T(x, y) = (1 + |x|^2 + |y|^2)^{-\frac{N-2}{2}}$$

already defined in (0.9). In order to simplify notations we set  $r = |x|$ ,  $s = |y|$ ,  $\eta := \frac{N+k}{2}$  and

$$\Gamma := \int_0^{+\infty} \frac{t^{N-k-1}}{(1+t^2)^{N-1}} dt, \quad \Phi_a := \int_0^{+\infty} \frac{r^{a+k-1}}{(1+r^2)^\eta} dr, \quad \Psi_a := \int_0^{+\infty} \frac{r^{\frac{N-a}{N-2}+k-1}}{(1+r^2)^\eta} dr .$$

We start with two identities, that can be proved via simple computations:

$$\int_0^{+\infty} \frac{t^{N-k-1}}{(1+t^2)^N} dt = \frac{N+k-2}{2(N-1)} \Gamma \tag{3.12}$$

$$\int_0^{+\infty} \frac{r^{a+k-1}}{(1+r^2)^{\eta-1}} dr = \frac{N+k-2}{N-2-a} \Phi_a \tag{3.13}$$

It turns out that

$$|\nabla v_T|^2 = (N-2)^2 \left[ \frac{1}{(1+r^2+s^2)^{N-1}} - \frac{1}{(1+r^2+s^2)^N} \right] .$$

First we compute, for every  $r$ ,

$$\begin{aligned} \int_0^{+\infty} \frac{s^{N-k-1}}{(1+r^2+s^2)^N} ds &= \frac{1}{(1+r^2)^N} \int_0^{+\infty} \frac{s^{N-k-1}}{\left(1 + \left(s(1+r^2)^{-\frac{1}{2}}\right)^2\right)^N} ds \\ &= \frac{1}{(1+r^2)^\eta} \int_0^{+\infty} \frac{t^{N-k-1}}{(1+t^2)^N} dt = \Gamma \frac{N+k-2}{2(N-1)} \frac{1}{(1+r^2)^\eta} \end{aligned}$$

by (3.12). In the same way one gets

$$\int_0^{+\infty} \frac{s^{N-k-1}}{(1+r^2+s^2)^{N-1}} ds = \Gamma \frac{1}{(1+r^2)^{\eta-1}} .$$

Set  $c_{N,k} := \omega_k \omega_{N-k}$ , and compute

$$\begin{aligned} \int_{\mathbb{R}^N} |x|^a |\nabla v_T|^2 d\xi &= c_{N,k} (N-2)^2 \int_0^{+\infty} r^{a+k-1} dr \int_0^{+\infty} |\nabla v_T|^2 s^{N-k-1} ds \\ &= c_{N,k} \Gamma (N-2)^2 \left( \int_0^{+\infty} \frac{r^{a+k-1}}{(1+r^2)^{\eta-1}} dr - \frac{N+k-2}{2(N-1)} \int_0^{+\infty} \frac{r^{a+k-1}}{(1+r^2)^\eta} dr \right) \\ &= c_{N,k} \Gamma (N-2)^2 \frac{N+k-2}{2(N-1)} \frac{N+a}{N-2-a} \Phi_a \end{aligned}$$

by (3.13). We also compute

$$\begin{aligned} \int_{\mathbb{R}^N} |x|^{\frac{Na}{N-2}} |v_T|^{2^*} d\xi &= c_{N,k} \int_0^{+\infty} r^{\frac{Na}{N-2}+k-1} dr \int_0^{+\infty} \frac{s^{N-k-1}}{(1+r^2+s^2)^N} ds \\ &= c_{N,k} \Gamma \frac{N+k-2}{2(N-1)} \Psi_a . \end{aligned}$$

Next, we use Hölder inequality (with conjugate exponents  $\frac{N}{N-2}$  and  $\frac{N}{2}$ ) to estimate

$$\Phi_a = \int_0^{+\infty} \frac{r^{a+k-1}}{(1+r^2)^\eta} dr \leq \Psi_a^{\frac{N-2}{N}} \Phi_0^{\frac{2}{N}} . \quad (3.14)$$

and we set

$$R_a := \frac{\int_{\mathbb{R}^N} |x|^a |\nabla v_T|^2 d\xi}{\left( \int_{\mathbb{R}^N} |x|^{\frac{Na}{N-2}} |v_T|^{2^*} d\xi \right)^{\frac{N-2}{N}}} ,$$

in such a way that  $S = R_0$  and  $S_{a,2^*}^D \leq R_a$ . From the above equality we get

$$S = \left( c_{N,k} \Gamma \frac{N+k-2}{2(N-1)} \Phi_0 \right)^{\frac{2}{N}} N(N-2) \quad (3.15)$$

since  $\Psi_0 = \Phi_0$ . Therefore, using also (3.14) and (3.15), we can estimate

$$S_{a,2^*}^D \leq R_a \leq \left( c_{N,k} \Gamma \frac{N+k-2}{2(N-1)} \Phi_0 \right)^{\frac{2}{N}} (N-2)^2 \frac{N+a}{N-2-a} = S \frac{N-2}{N} \frac{N+a}{N-2-a} .$$

The conclusion readily follows.  $\square$

We can get new sufficient conditions for (3.11) in the special case  $N = 2(k-1)$ . Indeed, in this case the exponent  $p_k$  defined in (3.2) coincides with the critical exponent  $2^*$ . The arguments and the computations of Lemma 3.2, together with the existence Theorem 3.6 and the uniqueness result in [13] lead to the following result.

**Lemma 3.8** *Inequality (3.11) holds true if  $2 < k < N$ ,  $N = 2(k-1)$  and  $-\frac{N+2}{2^*} < a < -\frac{N}{2^*}$ .*

We summarize here the existence/multiplicity results known up to now in the critical case.

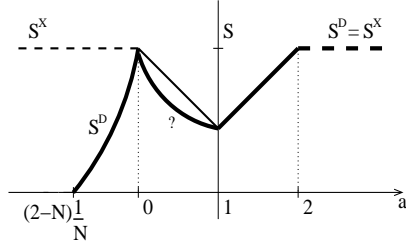
**Theorem 3.9 (existence)** *Assume  $(2-N)\frac{k}{N} < a \leq 2-k$ . If  $k=1$  and  $N=3$  assume in addition that  $a \leq 0$ . Then problem (3.9) has at least an entire solution  $u^D$  that achieves the best constant  $S_{a,2^*}^D$ .*

**Theorem 3.10 (multiplicity)** *Assume  $(2-N)\frac{k}{N} < a < 2-k$ . Then problem (3.9) has two distinct entire solutions:*

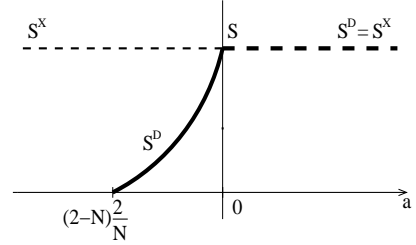
$$u^D \in D_0^1(\mathbb{R}^N; |x|^a d\xi) \setminus L^2(\mathbb{R}^N; |x|^{a-2} d\xi) , \quad u^X \in D_0^1(\mathbb{R}^N; |x|^a d\xi) \cap L^2(\mathbb{R}^N; |x|^{a-2} d\xi)$$

if one of the following conditions is satisfied:

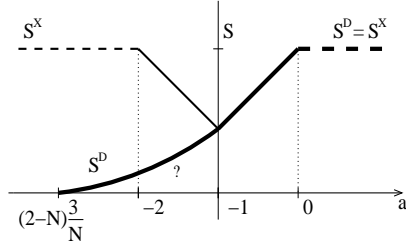
- $k = \frac{N+2}{2}$ ;
- $k = 3$ ,  $N \geq 7$  and  $a = -2$ ;
- $k = 3$ ,  $N = 5, 6$ , or  $k \geq 4$  and  $a$  is close enough to  $(2 - N)k/N$ .



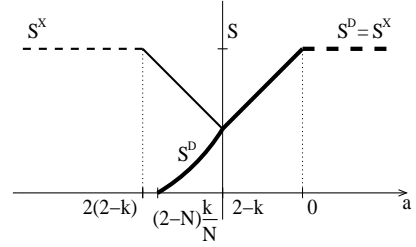
**Fig.2**  $k = 1$  and  $N \geq 4$ .



**Fig.3**  $k = 2$ .



**Fig.4**  $k = \frac{N+2}{2}$ .



**Fig.5**  $k = 3$  and  $N \geq 7$ .

**Remark 3.11** We do not know whether  $S_{a,2^*}^D < S_{a,2^*}^X = S$  holds true if  $k = 1$ ,  $N = 3$  and  $a \in (0, 1)$ . If  $k = 1$ ,  $N \geq 4$  and  $a \in (0, 1)$  we know that  $S_{a,2^*}^D, S_{a,2^*}^X$  are both achieved, but we do not know if  $S_{a,2^*}^D < S_{a,2^*}^X$ . The same question is still open if  $k \geq 3$  and  $a \in (2(2-k), 2-k)$ , unless  $N = 2(k+1)$ .

## 4 Existence results for (0.7)

In this section we deal with classical solutions to problem (0.7) under the assumption

$$\lambda \leq \lambda_1(0) = \left(\frac{k-2}{2}\right)^2.$$

In particular, solutions  $u$  we are looking for satisfy  $\int_{\mathbb{R}^N} |x|^{-b_0} |u|^p d\xi < +\infty$ , even if they might be singular, in the sense that one or both of the integrals

$$\int_{\mathbb{R}^N} |\nabla u|^2 d\xi, \quad \int_{\mathbb{R}^N} |x|^{-2} |u|^2 d\xi$$

might be unbounded. We distinguish the cases  $\lambda = \lambda_1(0)$  and  $\lambda < \lambda_1(0)$ .

#### 4.1 Existence for $\lambda = \lambda_1(0)$

In this Subsection we study problem

$$\begin{cases} -\Delta v = \left(\frac{k-2}{2}\right)^2 |x|^{-2} v + |x|^{-b_0} v^{p-1} & \text{in } \mathbb{R}^N, x \neq 0 \\ v > 0, \end{cases} \quad (4.1)$$

where  $p > 2$ ,  $p \leq 2^*$  if  $N \geq 3$ , and  $b_0 = N - p\frac{N-2}{2}$ . We are going to give an alternative proof of a result by Tertikas and Tintarev [16], that works also for  $p \in (2, 2^*)$  and  $N \geq 2$ .

**Theorem 4.1** *Problem (4.1) has a cylindrically symmetric classical solution  $v$  such that*

$$\int_{\mathbb{R}^N} |x|^{-b_0} |v|^p d\xi = \int_{\mathbb{R}^N} [|\nabla v|^2 - \lambda_1(0)|x|^{-2}|v|^2] d\xi < +\infty,$$

*provided that one of the following conditions are satisfied:*

- a)  $N = 2$  or  $p \in (2, 2^*)$ ;
- b)  $p = 2^*$ ,  $N \geq 4$  and  $k \neq 2$ .

**Proof.** Our aim is to prove that the infimum

$$\hat{S}_p := \inf_{v \in \hat{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k})} \frac{\int_{\mathbb{R}^N} [|\nabla v|^2 - \lambda_1(0)|x|^{-2}|v|^2] d\xi}{\left(\int_{\mathbb{R}^N} |x|^{-b_0} |v|^p d\xi\right)^{2/p}}$$

is achieved by a map  $v \in \hat{X}_0^1(\mathbb{R}^k \times \mathbb{R}^{N-k})$  that solves problem (4.1). This can be done directly, arguing as in Section 2, or it can be obtained as a Corollary to Theorem 2.1. Indeed, by Lemma 1.5 it is clear that the minimization problems  $\hat{S}_p$  and  $S_{2-k,p}^D$  are completely equivalent, in the sense that  $u \in D_0^1(\mathbb{R}^N; |x|^{2-k} d\xi)$  achieves  $S_{2-k,p}^D$  if and only if  $v = L_{2-k} u$  achieves  $\hat{S}_p$ . Then Theorem 2.1 easily leads to existence. The symmetry follows from Theorem 0.3 in [10].  $\square$

**Remark 4.2** We remark that the existence result in Theorem 4.1 does not hold for spherically symmetric weights (case  $k = N$ ). Indeed, it has been proved in [2] that for  $k = N$  and  $\lambda = \left(\frac{N-2}{2}\right)^2$  problem (0.7) has no distributional solutions in  $L_{\text{loc}}^1(\mathbb{R}^N \setminus \{0\})$ .

## 4.2 Existence of singular solutions for $\lambda < \lambda_1(0)$

Here we study problem (0.7) in case  $\lambda < \lambda_1(0) = \left(\frac{k-2}{2}\right)^2$ . A first solution  $v^X \in D_0^1(\mathbb{R}^N) \cap L^2(\mathbb{R}^N; |x|^{-2}d\xi)$  can be found by studying the minimization problem for the infimum  $S_{a,p}^X$  in (1.9). This was done in [15], Theorems 1 and 2. More precisely,  $S_{a,p}^X$  is achieved, provided that  $p < 2^*$ ; if  $p = 2^*$  then existence is proved if in addition  $\lambda > 0$ ,  $N \geq 4$  and  $k \neq 2$ .

Our aim is to use here the results in Sections 2 and 3 to find new classical solutions  $v \in L^p(\mathbb{R}^N; |x|^{-b_0}d\xi)$  to (0.7) that are *singular* in the sense that  $\int_{\mathbb{R}^N} |x|^{-2}|v|^2 d\xi$  diverges. Notice that Theorem 3.5 already provides the existence of a solution  $u \notin L^2(\mathbb{R}^N; |x|^{-2}d\xi)$  when  $k = 1$ ,  $\lambda = 0$  and  $p \in (2_*, 2^*)$ .

To handle the case  $k \geq 1$  we use a simple trick: assume

$$\lambda_1(0) - \left(\frac{N-k}{N}\right)^2 < \lambda < \lambda_1(0), \quad \frac{2(N-k)}{N-k-2\sqrt{\lambda_1(0)-\lambda}} < p \leq 2^*, \quad (4.2)$$

and define

$$a = a_{k,\lambda} := 2 - k - 2\sqrt{\lambda_1(0) - \lambda}.$$

Notice that with this choice, assumptions (0.3) on  $a$  and  $p$  are satisfied by (4.2). Moreover, it turns out that  $b_a = N - p\frac{N-2+a}{2} = b - \frac{pa}{2}$ , accordingly with (0.2). Assume that  $u$  is a solution to (0.1) with respect to this choice of the parameters  $a, b$  and with respect to the same  $p$ . Then the map

$$v = L_a u := |x|^{\frac{a}{2}} u$$

is a  $C^\infty(\mathbb{R}_0^N)$ -solution to (0.7). In addition, if for example  $u \in D_0^1(\mathbb{R}^N; |x|^a d\xi)$ , then

$$\int_{\mathbb{R}^N} |x|^{-b_0} |v|^p d\xi = \int_{\mathbb{R}^N} |x|^{-b_a} |u|^p d\xi < +\infty.$$

On the other hand, since  $a < 2 - k$ , then it might happen that  $u \notin L^2(\mathbb{R}^N; |x|^{a-2} d\xi)$ . If this is the case then  $\int |x|^{-2} v^2 = +\infty$ . By Hardy inequality, in case  $k > 2$  we have also that

$$\int_{\mathbb{R}^N} |\nabla v|^2 d\xi = +\infty.$$

In conclusion, through the functional change  $L_a$ , we can construct a singular solution to (0.7) starting from any solution  $u \in D_0^1(\mathbb{R}^N; |x|^a d\xi) \setminus X_0^1(\mathbb{R}^N; |x|^a d\xi)$  of problem (0.1). Thus, the results in Section 3.1 lead to the following existence result.

**Theorem 4.3** *Assume  $1 \leq k < N$ ,  $p > 2$  and  $p \leq 2^*$  if  $N \geq 3$ . Then problem (0.7) has a solution  $v_\infty \in L^p(\mathbb{R}^N; |x|^{-b_0} d\xi)$  that satisfies*

$$\int_{\mathbb{R}^N} |x|^{-2} v^2 d\xi = +\infty,$$

*provided that one of the following conditions is satisfied:*



- i)  $p \leq 2^*$  and  $p \left( N - k - 2\sqrt{\lambda_1(0) - \lambda} \right)$  is close enough to  $2(N - k)$ ;
- ii)  $p = p_k = \frac{2(N-k+1)}{N-k}$ ,  $2 \leq k \leq \frac{N+2}{2}$  and  $\lambda_1(0) - p_k^{-2} < \lambda < \lambda_1(0)$ ;
- iii)  $p = 2^*$ ,  $k = 1, 2$  and  $\lambda_1(0) - \left(\frac{N-k}{N}\right)^2 < \lambda < 0$ ;
- iv)  $p = 2^*$ ,  $k = 3$ ,  $N \geq 7$  and  $\frac{1}{4} - \left(\frac{N-3}{N}\right)^2 < \lambda \leq 0$ ;

We remark also the following immediate consequence to iv) of Theorem 4.3, and to Theorem 0.3 in [10].

**Corollary 4.4** *Assume  $N \geq 7$ . Then the equation*

$$-\Delta v = v^{2^*-1} \quad \text{on } (\mathbb{R}^3 \setminus \{0\}) \times \mathbb{R}^{N-3}$$

*has a positive smooth cylindrically symmetric solution  $v_\infty$  such that*

$$\int_{\mathbb{R}^N} |v_\infty|^{2^*} d\xi < S^{N/2}, \quad \int_{\mathbb{R}^N} |\nabla v_\infty|^2 d\xi = +\infty.$$

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